

Faculty of Engineering

Computer and Systems Engineering Department

**CSE 371: Control Systems (1)**

Instructor: Prof. Wahied Gharieb Ali

Micro-Project

**PID Controller**

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Table of Contents

[List of Figures 3](#_Toc439023502)

[1. PROBLEM FORMULATION 4](#_Toc439023503)

[2. Background 4](#_Toc439023504)

[3. Analysis 4](#_Toc439023505)

[4. Simulation 5](#_Toc439023506)

[4.1. Closed Loop System Simulation 5](#_Toc439023507)

[4.2. Disturbance Effect on The System 5](#_Toc439023508)

[4.3. Phase and Gain Margin for Open Loop System 6](#_Toc439023509)

[4.4. Phase and Gain Margin for Closed Loop System 7](#_Toc439023510)

[5. Conclusion 9](#_Toc439023511)

[6. REferences 9](#_Toc439023512)

# List of Figures

[Figure 1 Closed loop system response 5](#_Toc439023444)

[Figure 2 Closed loop system response with disturbance 5](#_Toc439023445)

[Figure 3 Using Matlab to calculate Pm and Gm of the open loop system 6](#_Toc439023446)

[Figure 4 Matlab results of the open loop system 6](#_Toc439023447)

[Figure 5 Bode plot of the open loop system 7](#_Toc439023448)

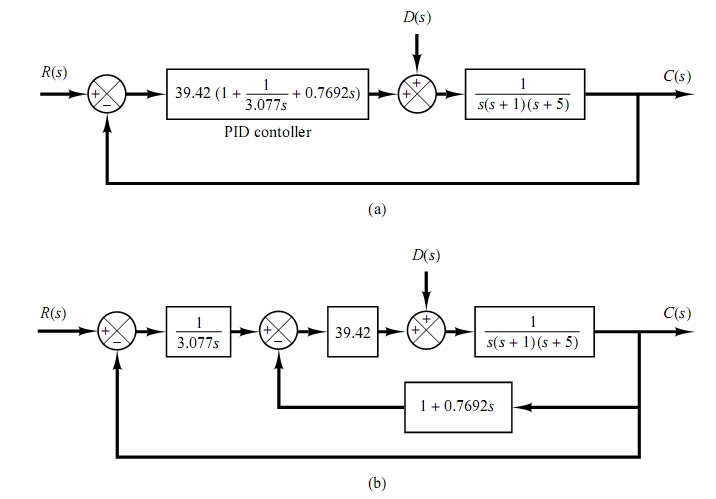
[Figure 6 Using Matlab to calculate Pm and Gm of the closed loop system 7](#_Toc439023449)

[Figure 7 Matlab results of the closed loop system 8](#_Toc439023450)

[Figure 8 Bode plot of the closed loop system 9](#_Toc439023451)

# PROBLEM FORMULATION

For the given system,



1. Simulate the closed loop system using the MATLAB/SIMULINK for a unit step input u(t)
2. Explain, which parameter in the PID block has to be modified to decrease the settling time.
3. Study the effect of a constant disturbance input = ±0.1u(t) on the system response.
4. Compute the gain margin and phase margin for the open loop without PID controller and closed loop system with PID controller.

# Background

The PID is the most popular feedback controller algorithm used. It is a robust easily understood algorithm that can provide excellent control performance despite the varied dynamic characteristics of processes.

The PID algorithm consists of three basic modes: the Proportional mode, the Integral mode & the Derivative mode.

In the *s*-domain, the PID controller may be represented as:

In the time domain:

u(t): The PID output

e(t): The Error between the output and the set point.

Kp: Proportional Gain

Ki: Integral Gain

Kd: Derivative Gain

# Analysis

# Simulation

## Closed Loop System Simulation

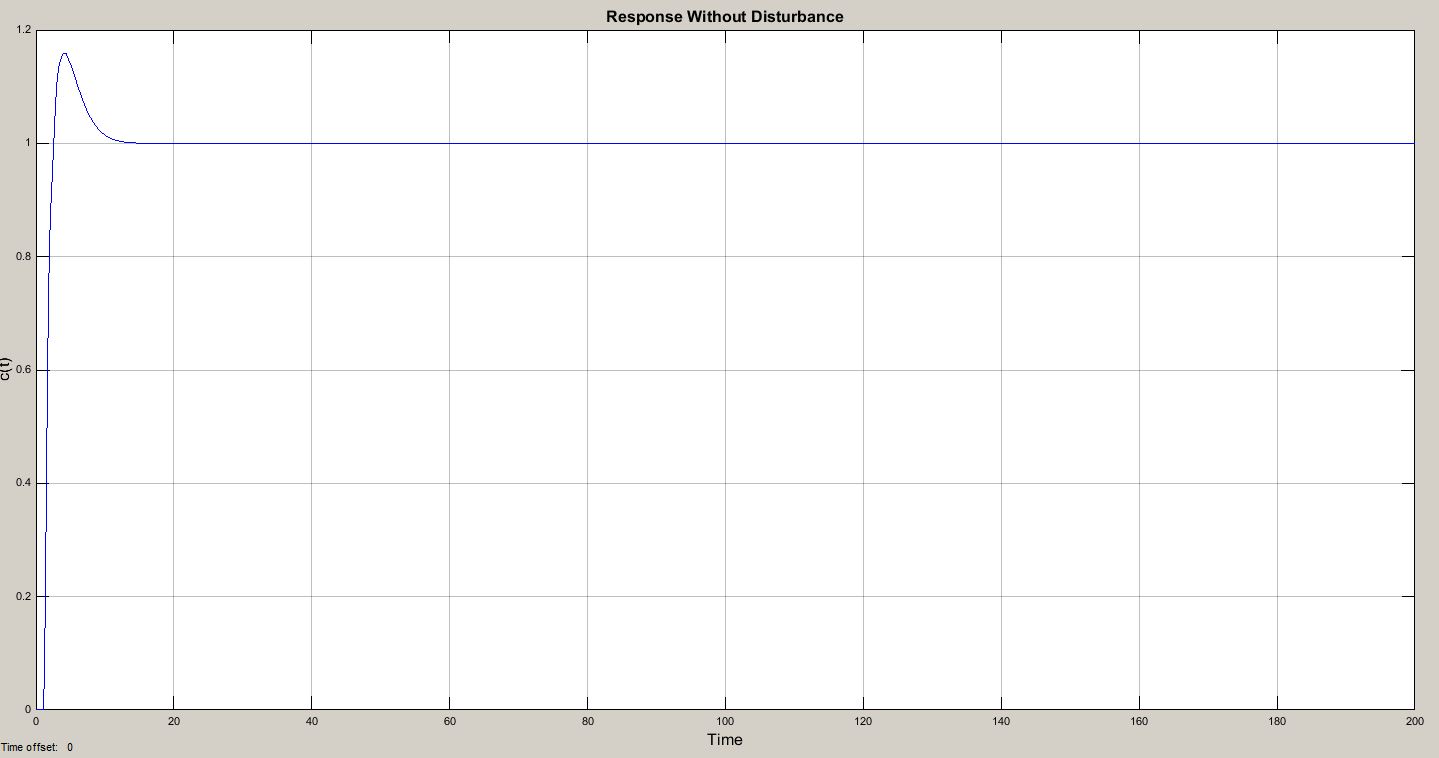


Figure 1 Closed loop system response

## Disturbance Effect on The System

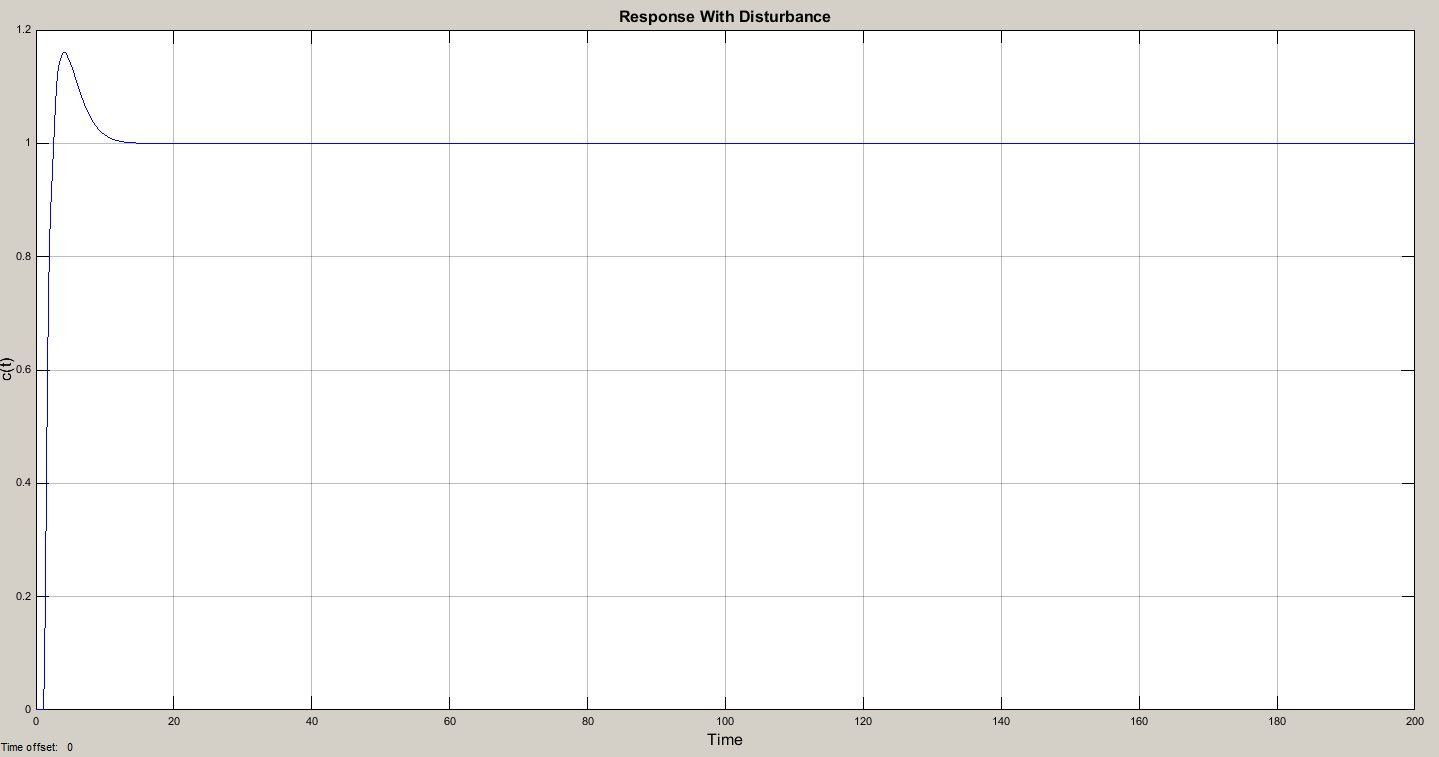


Figure 2 Closed loop system response with disturbance

## Phase and Gain Margin for Open Loop System

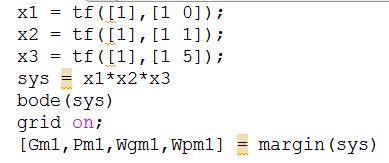


Figure 3 Using Matlab to calculate Pm and Gm of the open loop system

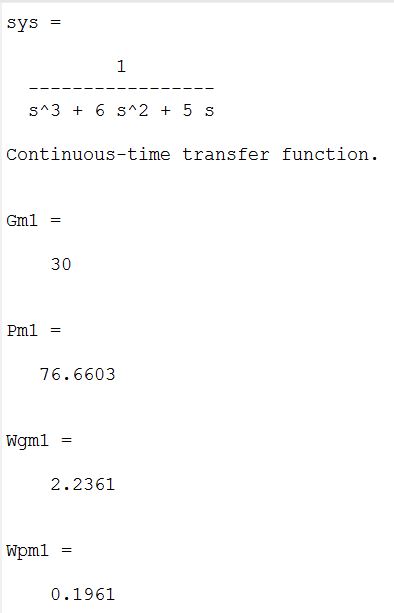


Figure 4 Matlab results of the open loop system

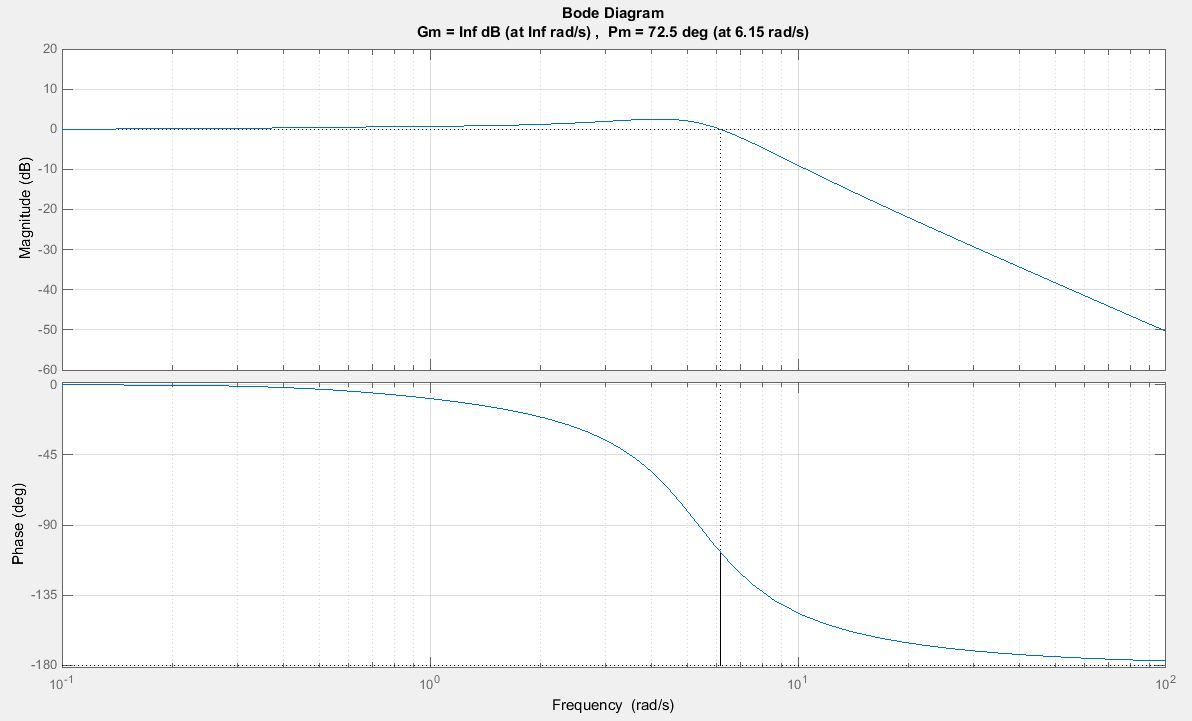


Figure 5 Bode plot of the open loop system

## Phase and Gain Margin for Closed Loop System

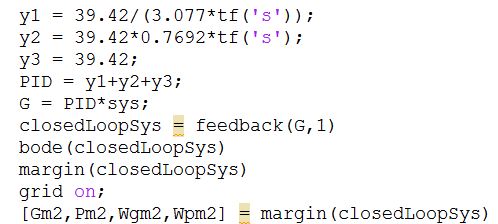


Figure 6 Using Matlab to calculate Pm and Gm of the closed loop system

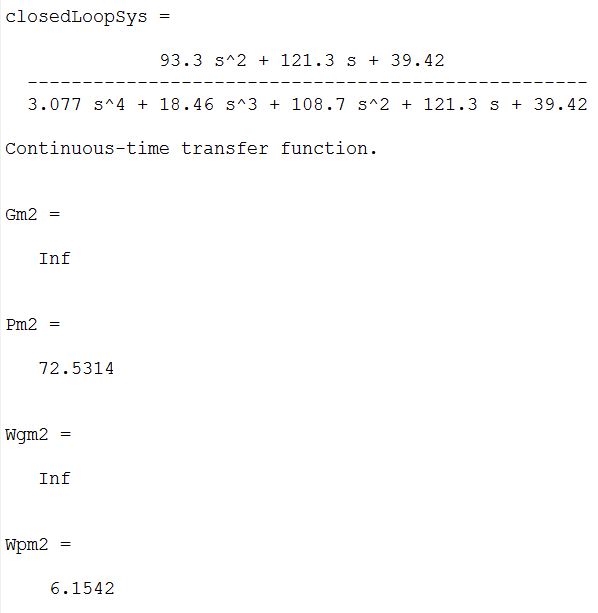


Figure 7 Matlab results of the closed loop system

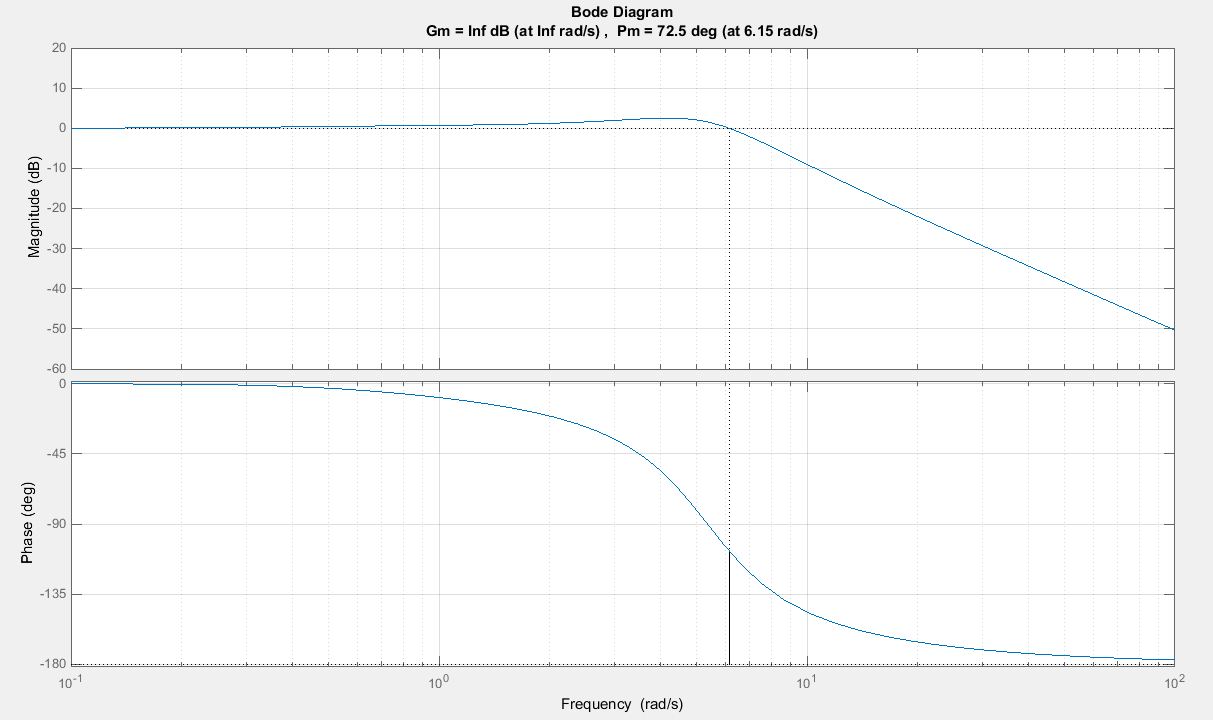


Figure 8 Bode plot of the closed loop system

# Conclusion

# REferences

[1] “Modern Control Engineering”, 5th edition, Katsuhiko Ogata.

[2] Lecture Slides: “Topic#11 PID Controller Design”, Dr. Wahid Gharib, 2015.